

# How to build someone we can talk to

Jonathan Mugan Øjmugan

Data Day Texas January 28th, 2023

### So many have left us

Many intelligent robots have come and gone, failing to become a commercial success



https://commons.wikimedia.org/wiki/File:Rethink\_Robotics\_%E2%80%94\_Brooks\_and\_Baxter\_%288000143255%29.jpg Steve Jurvetson from Los Altos, USA, CC BY 2.0 <https://creativecommons.org/licenses/by/2.0>, via Wikimedia Commons



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# Romo is gone



Jibo never seemed to get off the ground

Cynthiabreazeal, CC BY-SA 4.0 <https://creativecommons.org/licenses/by-sa/4.0>, via Wikimedia Commons Mighty Sony couldn't make Aibo stay



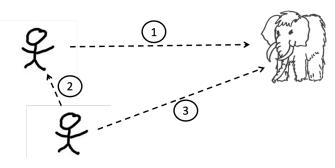
#### Even Alexa is reducing staff

These robots didn't reach their potential because you can't talk to them, not really.



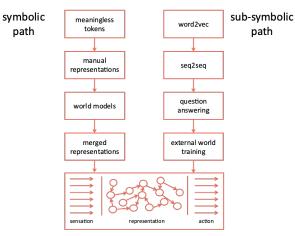
https://arstechnica.com/gadgets/2022/11/amazon-alexa-is-a-colossal-failure-on-pace-to-lose-10-billion-this-year/

#### Data Day 2017



Talked about how language evolved and the current state-of-the-art for chatbots and how they won't work without understanding

#### Data Day 2019



Talked about two paths to getting understanding

#### Data Day 2021



Data Day 2018 h4 zenerated meaning space text

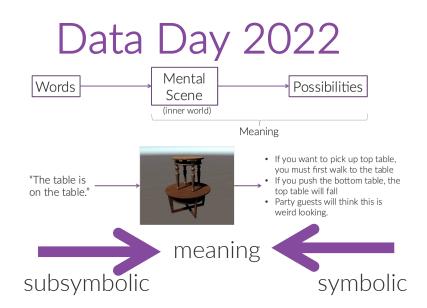
Attentio

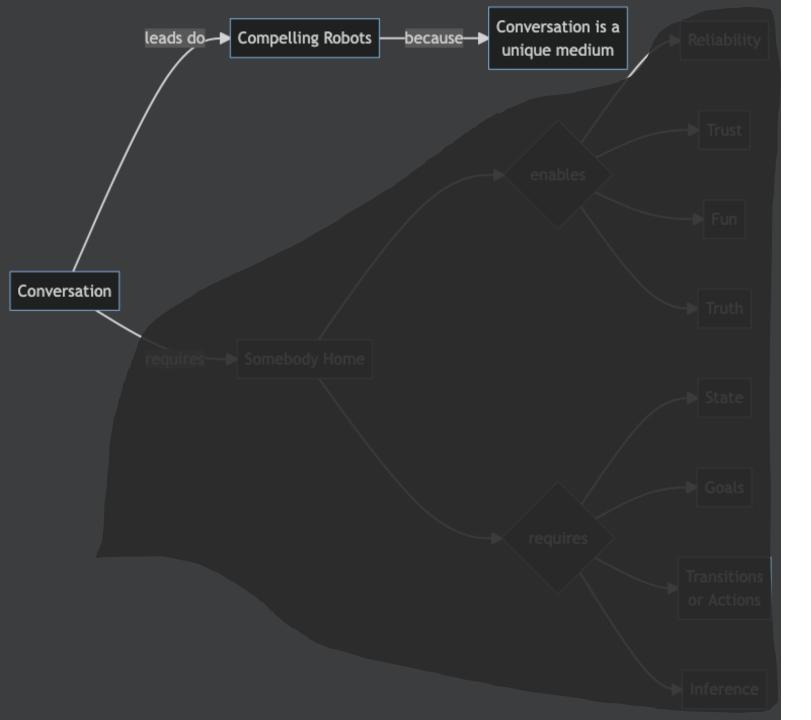
Went into detail about how neural networks can generate text

#### Data Day 2020 Data Ingestion (ExampleGen) TensorFlow Data Validation StatisticsGen, SchemaGen, Example Validator) We got TensorFlow Transform distracted and (Transform) Estimator or Keras Model did MLOps with (Trainer)

(Pusher)



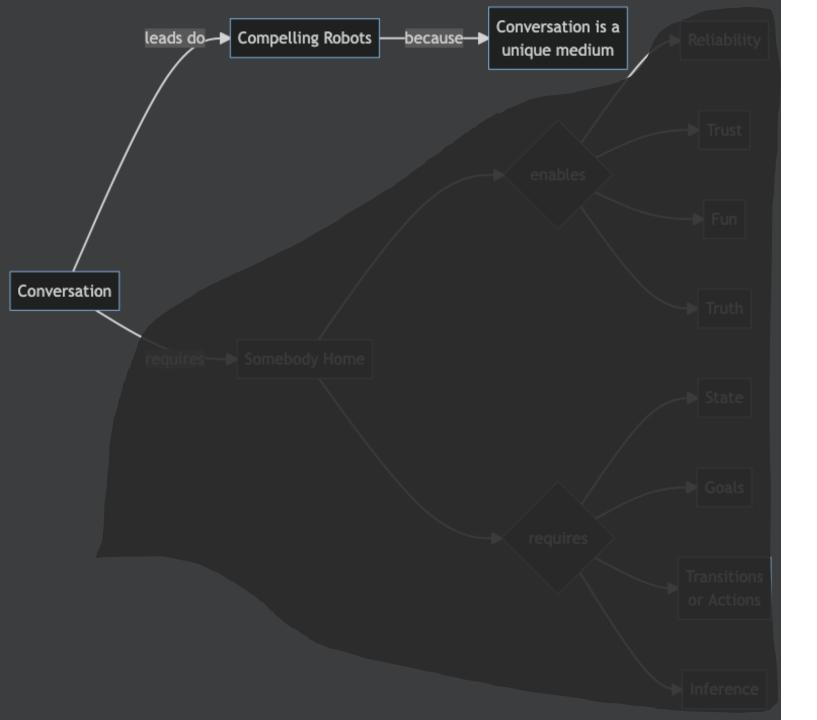




# Conversation is a unique medium

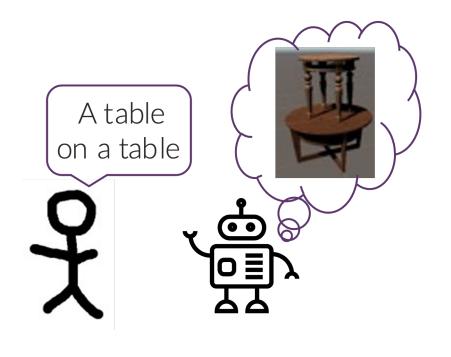
Conversations are interactive

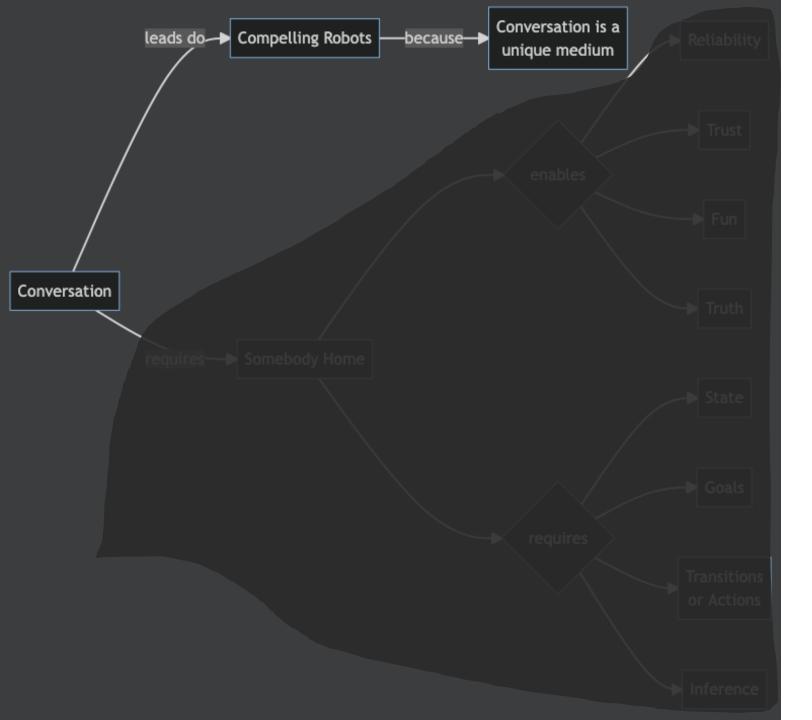
- but they are also hyperlocal and hyper-specific to the current context
- context entails the current situation and conversation history



# Conversation is a unique medium

When you have a conversation with someone, you direct their imagination and they yours

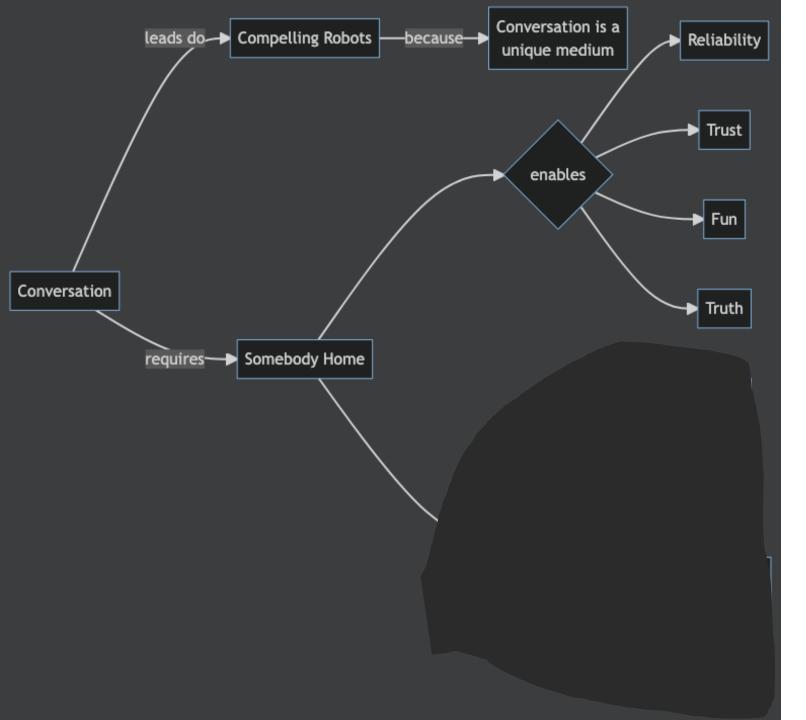




# Conversation is a unique medium

We don't have any other medium that has those properties

- movies, tv, videos, don't
- The best conversations teach
- Conversation is one of the hardest things we do as humans—why they say people need to socialize to keep their thinking sharp

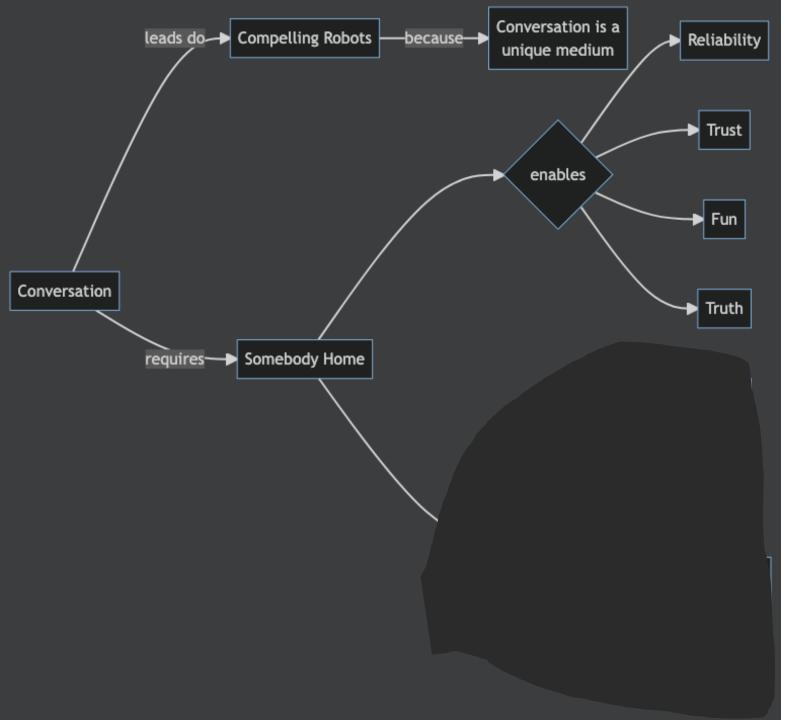


# Why a conversation partner needs to be "somebody"

**Reliability**: If it represents the world the way that we do less likely to make a catastrophic mistake (since its knowledge structure

is built on our representation)

Trust: need the mistakes it does make to make sense to us

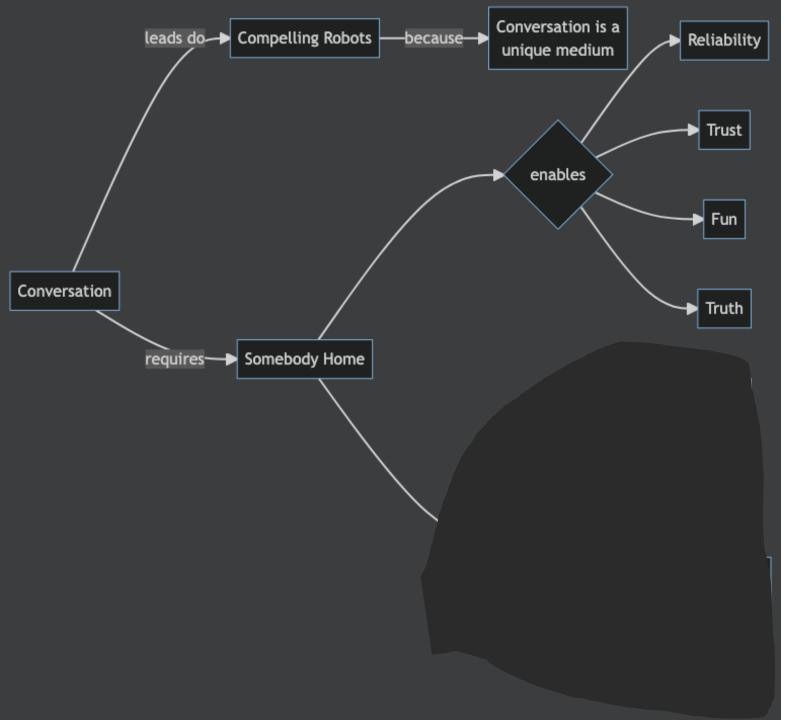


# Why a conversation partner needs to be "somebody"

Fun: much more interesting to talk to somebody.

#### Consider the humor

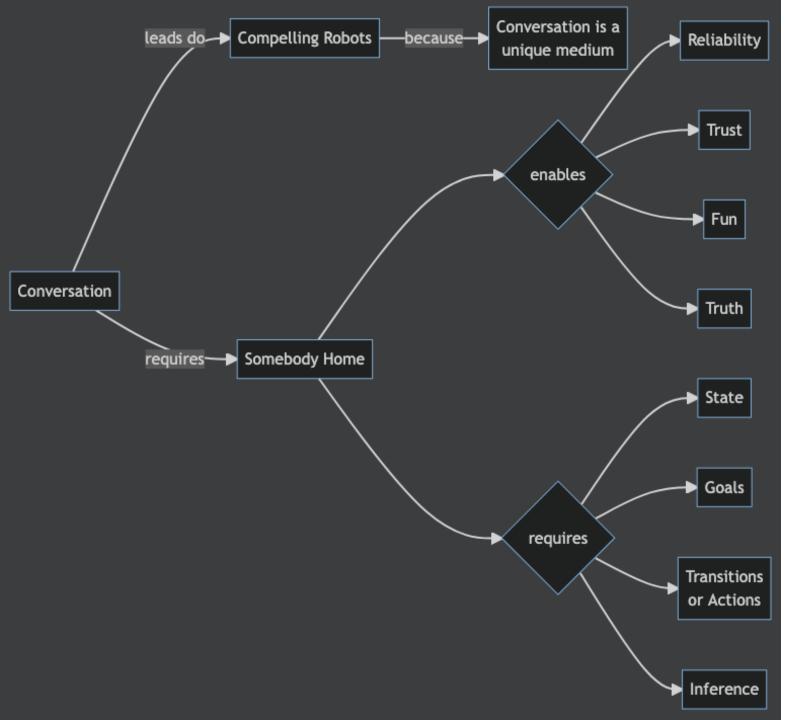
- Household robot: should have some goal obscure to the owner, like tapping on the walls. "What the hell is it doing?"
- NPC: "You're playing a video game, right? Can you get me out of here?"



# Why a conversation partner needs to be "somebody"

#### Truth: most important

- Truth comes from interaction with the real world
- A person seeks to bend the world to their goals
  - A person strives for things
- ChatGPT: you can kind-of have a conversation with it, but it isn't there



#### Somebody home requires

#### State

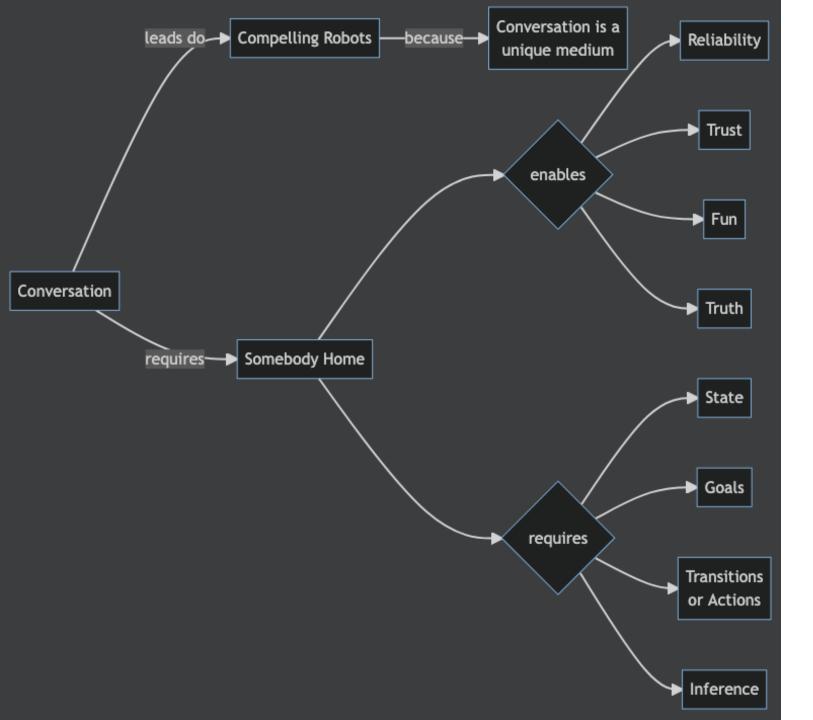
• The world around it

#### Goals

- Transitions enable one to talk about goals
- Why would it talk at all?
  - Thinking beyond naturallanguage interface

#### Transitions (actions)

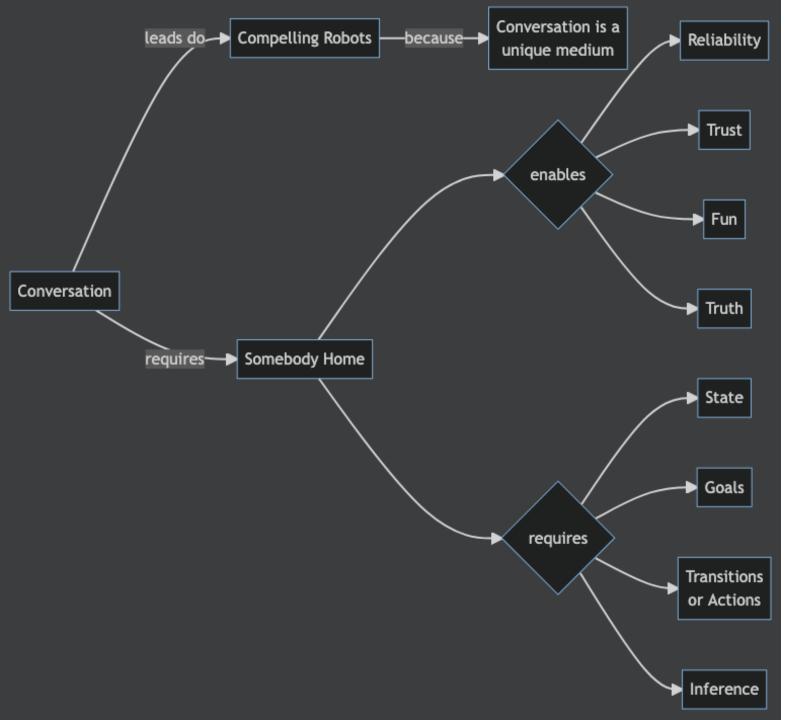
• How the world changes



### Somebody home requires

#### Inference

- Inference is mapping a continuous situation to some space of values
- Keeps us from being brittle
- See Eiffel tower, in Paris
- Back to Kant and before
  - He calls it Judgment
  - <u>https://plato.stanford.e</u> <u>du/entries/kant-</u> <u>judgment/</u>



### Somebody home requires

#### Inference

- Inference is mapping a continuous situation to some space of values
- Keeps us from being brittle
- See Eiffel tower, in Paris

"The Beginning of Infinity," by David Deutsch

- "People" are entities that can create explanations.
- When we see stars, we don't see what they are, we just see points of light.

## Inference has a precise formulation

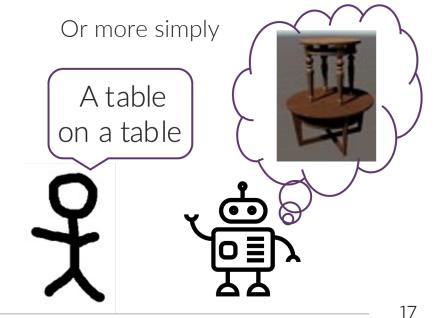
it's the Bayesian equation

$$P(hypothesis|observation) = \frac{P(observation|hypothesis)P(hypothesis)}{P(observation)}$$

#### $P(hypothesis|observation) \propto P(observation|hypothesis)P(hypothesis)$

*P(observation|hypothesis)* is your model of the world Hypothesis: is an explanation in the David Deutsch sense

"A big burning ball of hydrogen and helium burning millions of miles away might look like that"





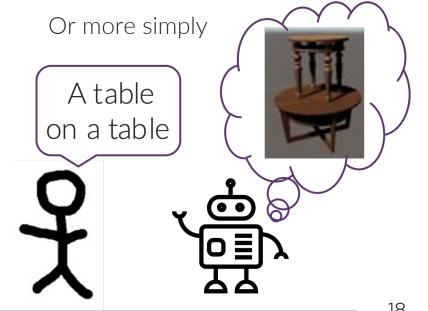
## **Inference has a precise formulation**

it's the Bayesian equation

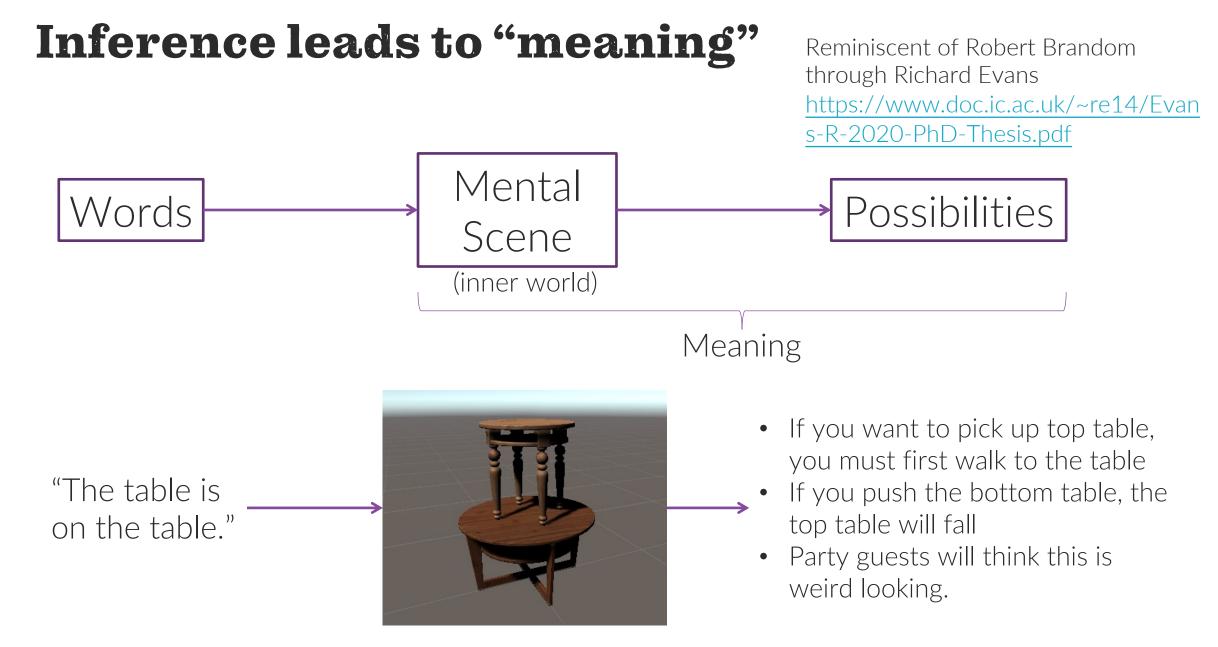
$$P(hypothesis|observation) = \frac{P(observation|hypothesis)P(hypothesis)}{P(observation)}$$

#### $P(hypothesis|observation) \propto P(observation|hypothesis)P(hypothesis)$

*P*(*observation*|*hypothesis*) must be composable and you have to come up with it on the fly

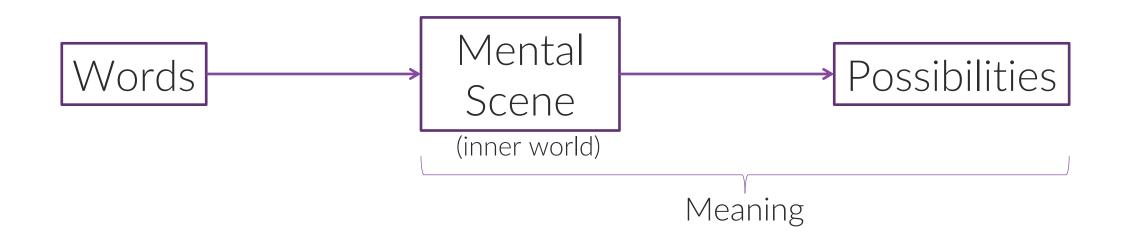






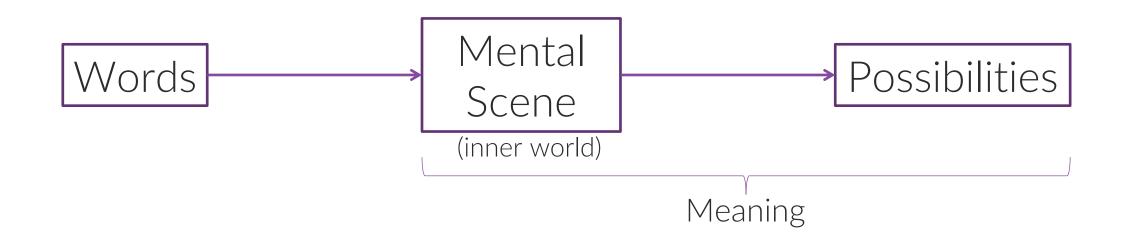


## Inference leads to "meaning"





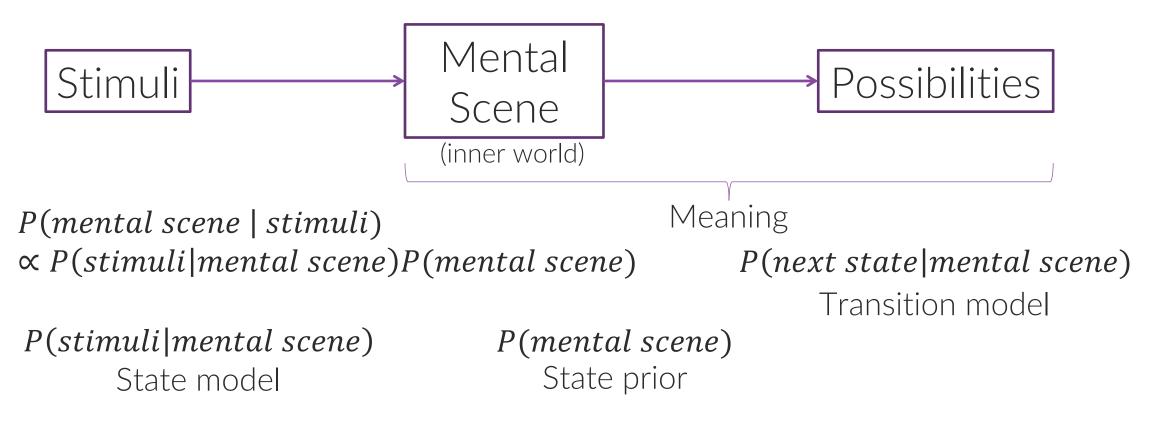
## Inference leads to "meaning"



Two ways to not understand in a conversation:1. Wrong mental scene2. Not knowing the possibilities



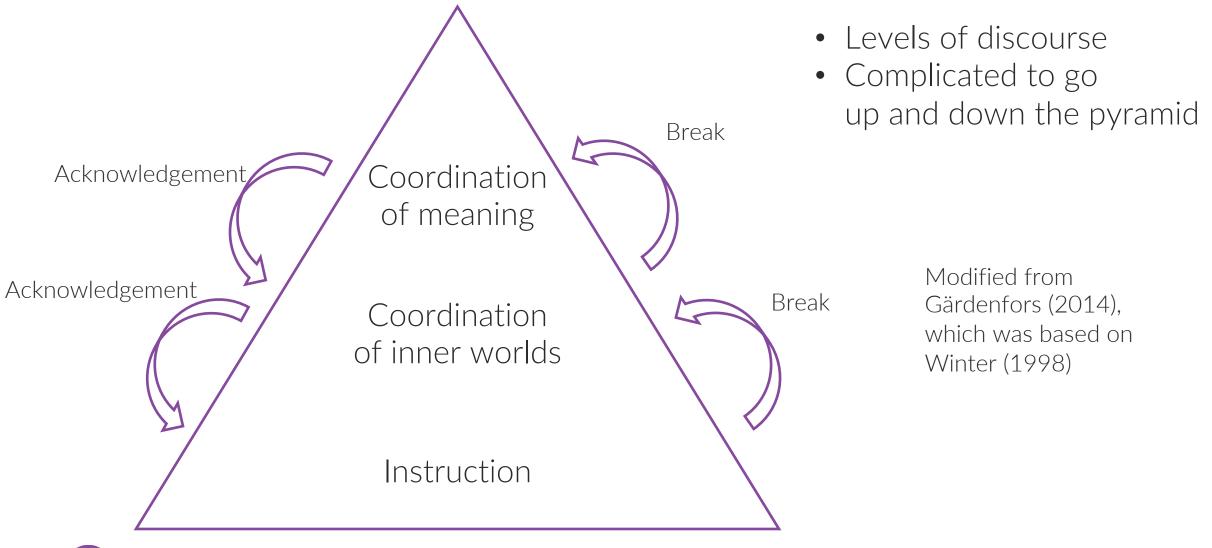
## Inference leads to "meaning"



- These two models must be composable.
- They must be dynamic and can't be precomputed, as we will see.

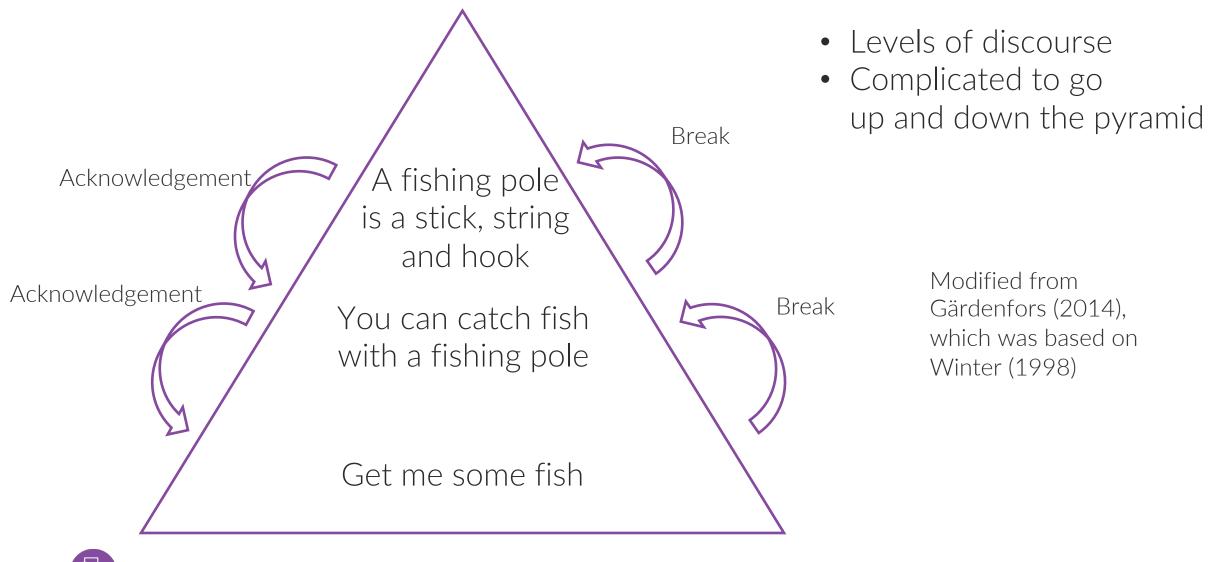


#### Inference for conversation requires dynamic composition





#### Inference for conversation requires dynamic composition



Umbra

# Inference is over more than words: conversation has its own rules (pragmatics)

- Conversational maxims: Grice (1975, 1978)
- Breaking these rules is a way to communicate more than the meaning of the words.

Maxim of Quantity: Say only what is not implied. Yes: "Bring me the table." No: "Bring me the table by transporting it to my loo What did she mean by that?	cation."
Maxim of Quality: Say only things that are true. Yes: "I hate carrying tables." No: "I love carrying tables, especially when they ar She must be being sarcastic.	e covered in fire ants."
Maxim of Relevance: Say only things that matter. Yes: "Bring me the table." No: "Bring me the table and birds sing." What did she mean by that?	
Maxim of Manner: Speak in a way that can be und Yes: "Bring me the table." No: "Use personal physical force to levitate the tab What did she mean by that?	



Words are only hints at possible meanings

When I saw this, my first thought was, "Where do people enter?"

# Our inference models need to compose for maximum coverage

Multiplicative: Most general sense, a bird that can drive a car

Foundational Metaphors (See Mark Johnson and others. Steven Pinker talks about two main ones)

- Force
  - An offer or a person can be *attractive*
  - A broken air conditioner can *force* you to move a meeting
- Location in space
  - Al has come *a long way* in the last 15 years

Analogies (Melanie Mitchell and Douglas Hofstadter)

• We can broadly apply the story of sour grapes (Hofstadter in Surfaces and Essences)

**Conceptual Blending** (*The Way We Think* by Gilles Fauconnier and Mark Turner)

- That running back is a truck
- Dall-e 2 could generate a good picture of this, but it couldn't imagine what it is like to tackle a vehicle



# **OpenAI Dall-e 2**

- Trained on combinations of images and text; <u>CLIP</u> and diffusion models
- Can create images from whatever you type

#### https://openai.com/dall-e-2/

Thanks to you <u>@hardmaru</u> for the images!

Prompt: "Darth Vader on the cover of Vogue magazine"



### Outline

- Conversation makes compelling robots and what conversation requires
- The symbolic path of autonomous simulation
- The sub-symbolic path of coaxing neural networks

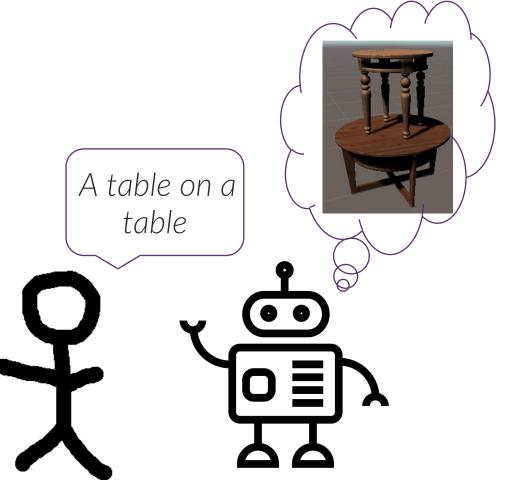


### Outline

- Conversation makes compelling robots and what conversation requires
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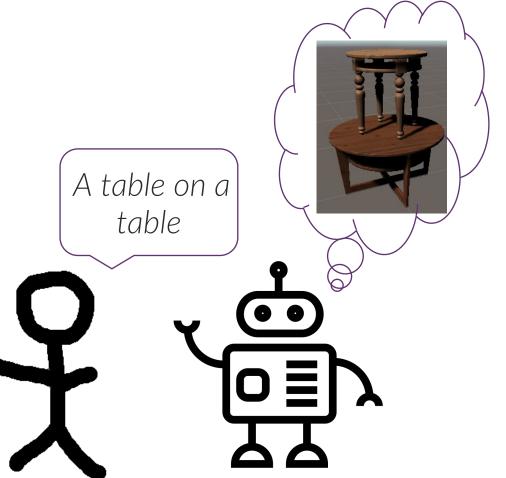
- One way to build supple intelligence is to have a robot build a simulation of its environment.
- The robot simulates what you say in something like Unity.



See "Computers could understand natural language using simulated physics" from 2017 for additional details. https://chatbotslife.com/computers-could-understand-natural-language-using-simulated-physics-26e9706013da



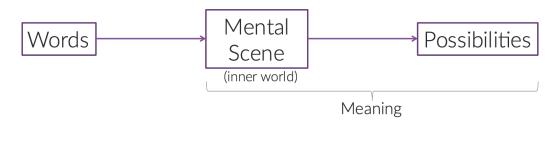
- Simulation enables robust inference because it provides an unbroken description of the dynamics of the environment, even if it is not complete in full detail.
- This unbroken description is a grounding.



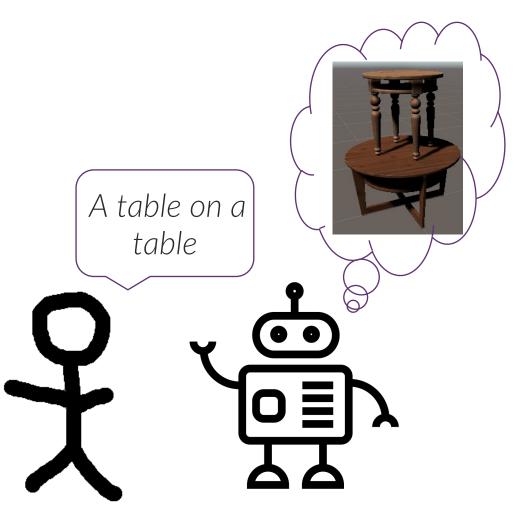
See "Computers could understand natural language using simulated physics" from 2017 for additional details. https://chatbotslife.com/computers-could-understand-natural-language-using-simulated-physics-26e9706013da



What will happen if I push the bottom table?



Well, mentally push it and see.



See "Computers could understand natural language using simulated physics" from 2017 for additional details. https://chatbotslife.com/computers-could-understand-natural-language-using-simulated-physics-26e9706013da



Classic AI question, can birds fly?

 $\forall x \ bird(x) \rightarrow can_fly(x)$ 

Okay, okay

 $\forall x \ bird(x) \land flying\_bird(x) \rightarrow can\_fly(x)$ 

Okay, okay

 $\forall x \ bird(x) \land flying\_bird(x) \\ \land not \ broken\_wing(x) \rightarrow can\_fly(x) \end{cases}$ 

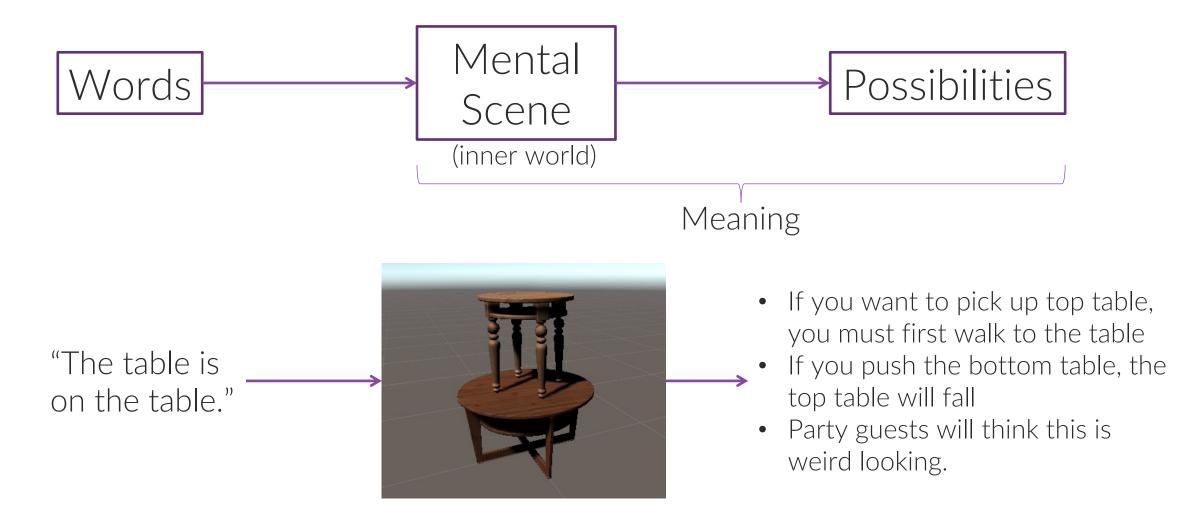


WKRP "As God as my witness, I thought turkeys could fly" https://www.youtube.com/watch?v=If3mgmEdfwg&ab\_channel=EpicHouston

Okay, okay, what if it is covered in maple syrup?



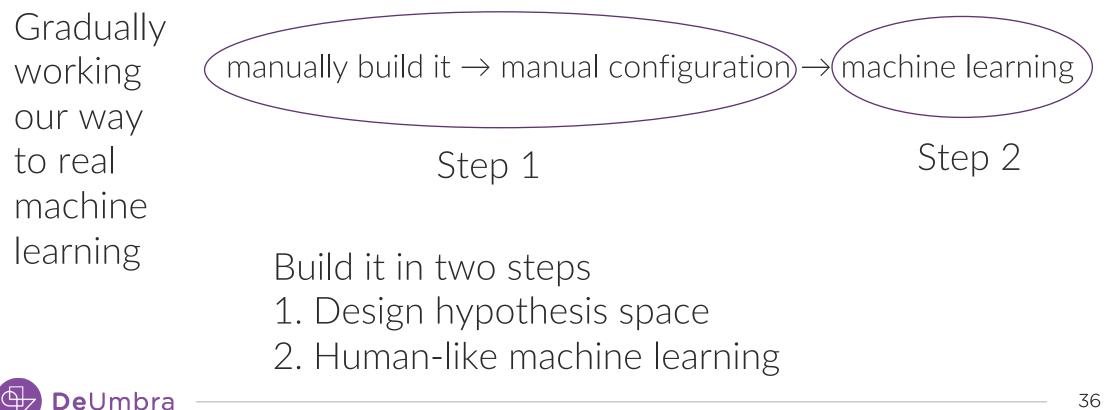
## The AI must build its own simulations



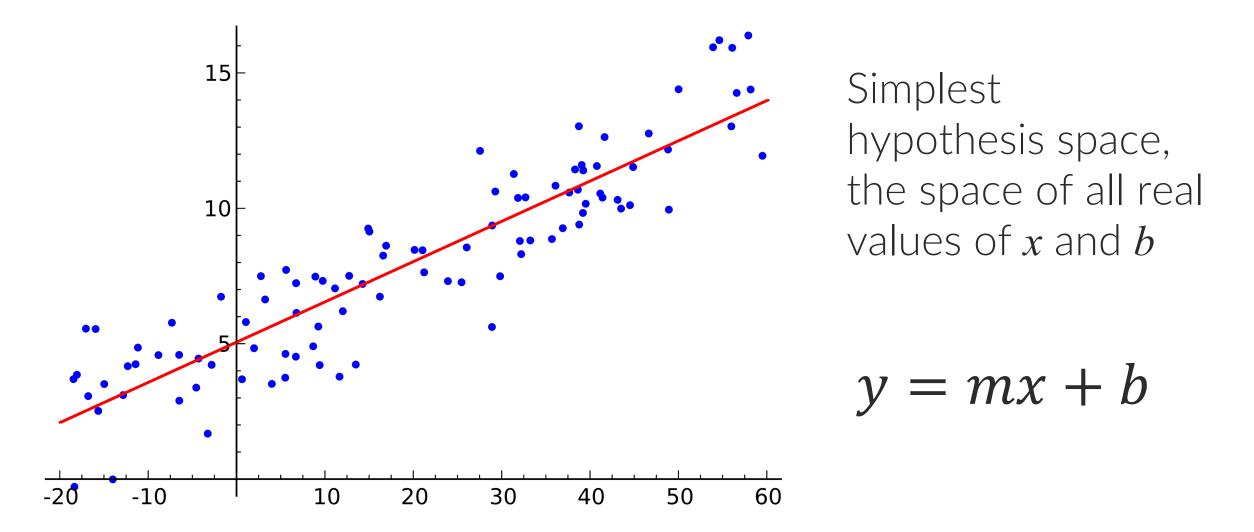


## How to Build an AI that Imagines through Simulation

We don't have to put as much information in as if we were using logic because the simulations will automatically combine things, but we still have a challenging problem ahead of us. How do we do it?



# The hypothesis space is the foundation of machine learning



By Sewaqu - Own work, Public Domain, <u>https://commons.wikimedia.org/w/index.php?curid=11967659</u>

# The hypothesis space is the foundation of machine learning

Recall from 2015

Neural networks are just millions of linear regressions with little nonlinear functions thrown in between the layers to keep it from squashing down. Deep learning begins with a little function

It all starts with a humble linear function called a perceptron.

weight1 ×input1 weight2 ×input2 weight3 ×input3

sum

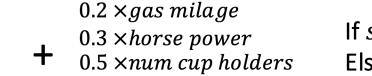
In math, with x being an input vector and w being a weight vector.

#### Perceptron:

If *sum > threshold*: output 1 Else: output 0

$$\operatorname{sum}(x) = \sum_{i=1}^{n} w_i \, x_i = w^T x$$

Example: The inputs can be your data. Question: Should I buy this car?



If *sum > threshold*: buy car Else: walk

### But it doesn't have to be simple like that

Structured hypothesis spaces

- Space of Bayesian networks
- Space of probabilistic programs
- Space of antenna shapes
- Space of relational database schemas
- Space of DNA sequences

Once you set up the space, then you can search in that

space

- Genetic algorithms
- Hillclimbing
- Backpropagation (like in neural networks, if the space is continuous)



Interlude: Best book if you are interested in the fundaments of machine learning

You can read it for free!

Tom Mitchell, "Machine Learning"

http://www.cs.cmu.edu/~tom/mlbook.html

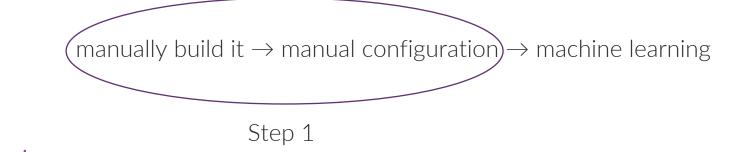
# So, we got to set up a particularly complicated hypothesis space

Domain, Classes, Relations <u>https://web.stanford.edu/~jurafsky/slp3/21.pdf</u>

Frames: frames, slots, classes, instances, types, and values

- My view: you can't get very far with formal representation and reasoning.
  - Even simple problems are hard.
  - Yale shooting problem <a href="https://en.wikipedia.org/wiki/Yale\_shooting\_problem">https://en.wikipedia.org/wiki/Yale\_shooting\_problem</a>
- Humans don't do it that way. We have to be taught *How the Mind Works*, Steven Pinker

So, it has to be some kind of embodied (problem specific) representation, but it needs to be structured enough that you can add to it without having to write Python code.





## Building the hypothesis space: Manual Configuration

	ECG Workbench	
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<ul> <li>ROOT</li> <li>InOrder</li> <li>Possession</li> <li>EventFeatures</li> <li>SerialProcessArgs</li> <li>Modification</li> <li>Prediction</li> <li>HasAgreementFeatures</li> <li>Sertily</li> <li>RDExtras</li> <li>ForceTransfer</li> <li>RD</li> <li>AVP</li> <li>CompressedMentalSpace</li> <li>RootType</li> <li>AgreementFeatureSet</li> <li>TemporalStage</li> <li>VerbKind</li> <li>Value</li> <li>Amount</li> <li>Directional</li> <li>Concessive</li> <li>WordForm</li> <li>MentalSpace</li> <li>ByLandmark</li> <li>EventDescriptor</li> <li>ArgForm</li> <li>At123</li> <li>Quantity</li> <li>Relation</li> <li>Process</li> <li>Metonymy</li> <li>TemporalModifier</li> </ul>	Image: Sentence: robot1, dash to box1!     Image: robot1, dash to box1! </th <th>● Grammar       Dutline       © Construct       N         ● Norder       ● Norder       ● Norder         ● Norder       ● Norder       ● Norder         ● Pall       ● Norder       ● Norder         ● Norder       ● Norder       ● Norder         ● Mord       ● Order       ● Norder         ● Mord       ● Order       ● Norder         ● Mord       ● ConditionalClusse       ● Order         ● Order       ● Norder       ● Norder         ● Mord       ● ConditionalClusse       ● Order         ● Morder       ● Order       ● Norder         ● Morder       ● Norder       ● Norder         ● Directional       ● Norder       ● N</th>	● Grammar       Dutline       © Construct       N         ● Norder       ● Norder       ● Norder         ● Norder       ● Norder       ● Norder         ● Pall       ● Norder       ● Norder         ● Norder       ● Norder       ● Norder         ● Mord       ● Order       ● Norder         ● Mord       ● Order       ● Norder         ● Mord       ● ConditionalClusse       ● Order         ● Order       ● Norder       ● Norder         ● Mord       ● ConditionalClusse       ● Order         ● Morder       ● Order       ● Norder         ● Morder       ● Norder       ● Norder         ● Directional       ● Norder       ● N
<ul> <li>S Extensions</li> <li>HeadingSchema</li> </ul>	Text Output SemSpec 1, cost -25.841331	
<ul> <li>TemporalSequence</li> <li>TrajectorLandmark</li> <li>TemporalInterval</li> </ul>	Problems      Console      Debug Console	
Scale		

Embodied construction grammar <a href="https://github.com/icsi-berkeley">https://github.com/icsi-berkeley</a>

### **Build for composability**

#### Multiplicative

• Build it so code reuses code with "duck" typing

#### Foundational Metaphors and Analogies

- Build it so code reuses code with "duck" typing
- Evolution progresses by finding new uses for existing structures

#### **Conceptual Blending**

• Focus on properties; create new objects using unions of properties.



# 2. Use the hypothesis space for machine learning

manually build it  $\rightarrow$  manual configuration  $\rightarrow$ (machine learning)

Step 2

With the right hypothesis space, we can do real machine learning. We don't need special algorithms; basic rule learning and decision-tree type stuff will be enough.

If A and B were there when great thing C happened, A and B are good and A,B  $\rightarrow$ C

Real (human-like) machine learning means you have all the pieces, you just have to label some subsets.



# 2. Use the hypothesis space for machine learning

manually build it  $\rightarrow$  manual configuration  $\rightarrow$  (machine learning)

Step 2

Different from the standard paradigm:

while not converged

run training examples through and update parameters based on errors

Real (human-like) machine learning means you have all the pieces, you just have to label some subsets.

Less of a pushing in continuous space and more of labeling groups.



# 2. Use the hypothesis space for machine learning

manually build it  $\rightarrow$  manual configuration  $\rightarrow$ (machine learning)

Step 2

Real (human-like) machine learning also means you have all the pieces those pieces should causally fit together

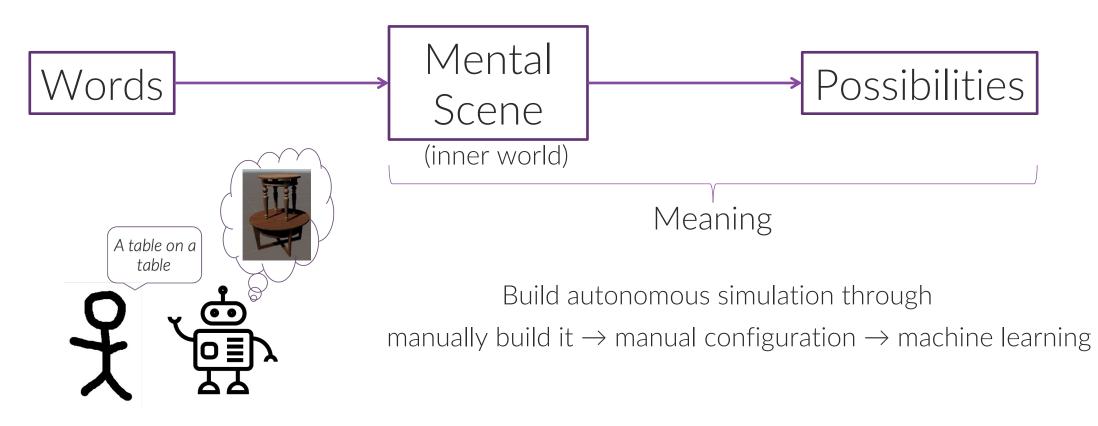
If A and B were there when great thing C happened, A and B are good and A,B  $\rightarrow$ C

Based on other associations between A and B and C there should be a causal mechanism that ties them together

"Oh, that makes sense because A  $\rightarrow$  M  $\rightarrow$  N and B  $\rightarrow$  Q and, of course and everyone knows that N&G $\rightarrow$ C"



# How to build someone to talk to using the symbolic method



You don't build an AI that can understand stories. You build an AI that can \*build\* stories. Then, it can "understand" stories by constructing a sequence of events that meets the constraints of the story.



### Outline

- Conversation makes compelling robots and what conversation requires
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In the context of natural language processing with the spaCy library, a "match\_id" is a unique identifier for a pattern match. This identifier can be used to refer to the specific match when working with the results of a matching operation.

To obtain the match\_id for a specific pattern match, you can use the `Span.get\_id()` method. This method is called on a `Span` object that represents the matched pattern, and it returns the match\_id as an integer.

Here is an example of how you might use this method to get the match\_id for a pattern match:

	Copy code
import spacy from spacy.matcher import Matcher	
<pre># Load a spaCy model and create the matcher nlp = spacy.load("en_core_web_sm") matcher = Matcher(nlp.vocab)</pre>	
<pre># Define a pattern to match pattern = [{"LOWER": "example"}, {"LOWER": "pattern"}]</pre>	
<pre># Add the pattern to the matcher and apply it to a text matcher.add("EXAMPLE_PATTERN", None, pattern) doc = nlp("This is an example of a pattern match.") matches = matcher(doc)</pre>	
<pre># Iterate over the matches and print the match_id for each one for match_id, start, end in matches:     matched_span = doc[start:end]     print(matched_span.get_id())</pre>	

In this example, the output would be the integer `0`, which is the match\_id for the first (and in this case, only) pattern match that was found in the text.

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# ChatGPT is amazing

G

To match a specific pattern by its match\_id, you can use the `Matcher.get\_pattern\_id()` method. This method is called on a `Matcher` object, and it takes the match\_id as an argument. It returns the pattern definition (i.e. the sequence of tokens that the pattern is intended to match) associated with the specified match\_id.

Here is an example of how you might use this method to get the pattern associated with the match\_id `o`:

	Copy code
import spacy	
from spacy.matcher import Matcher	
# Load a spaCy model and create the matcher	
<pre>nlp = spacy.load("en core web sm")</pre>	
matcher = Matcher(nlp.vocab)	
# Define a pattern to match	
<pre>pattern = [{"LOWER": "example"}, {"LOWER": "pattern"}]</pre>	
# Add the pattern to the matcher and apply it to a text	
<pre>matcher.add("EXAMPLE_PATTERN", None, pattern) </pre>	
<pre>doc = nlp("This is an example of a pattern match.")</pre>	
<pre>matches = matcher(doc)</pre>	
# Iterate over the matches and print the pattern associated with each one	
<pre>for match_id, start, end in matches:</pre>	
<pre>pattern_id = matcher.get_pattern_id(match_id)</pre>	
print(pattern_id)	

In this example, the output would be the pattern that we defined earlier: `[{"LOWER": "example"}, {"LOWER": "pattern"}]`. This is the pattern that was matched by the `Matcher` when it was applied to the text.

# ChatGPT is amazing

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Tools

🔍 All 🖾 Images 🔗 Shopping 🕞 Videos 💷 News

: More

About 1,240 results (0.43 seconds)

https://spacy.io > api > top-level

#### Top-level Functions · spaCy API Documentation

spaCy is a free open-source library for Natural Language Processing in Python. It features NER,

POS tagging, dependency parsing, word vectors and more.

Missing: get\_pattern\_id | Must include: get\_pattern\_id

https://spacy.io > usage > processing-pipelines

#### Language Processing Pipelines · spaCy Usage Documentation

spaCy is a free open-source library for Natural Language Processing in Python. It features NER,

POS tagging, dependency parsing, word vectors and more.

Missing: get\_pattern\_id | Must include: get\_pattern\_id

https://spacy.io > models

Trained Models & Pipelines · spaCy Models Documentation

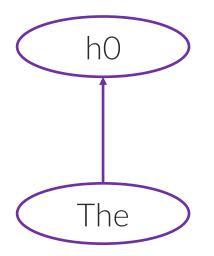
Downloadable trained pipelines and weights for spacy.

Missing: get\_pattern\_id | Must include: get\_pattern\_id

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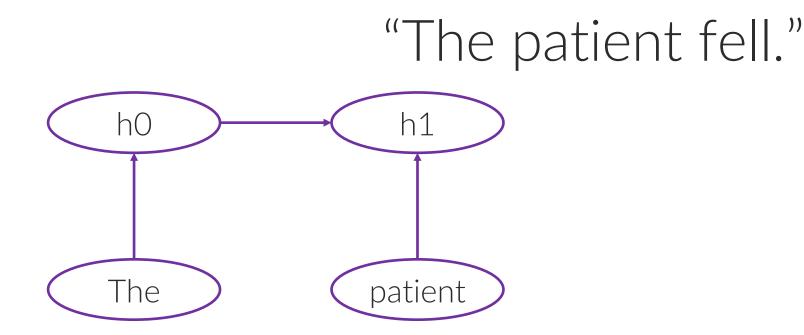
ChatGPT is amazing but it has no sense of truth

"The patient fell."



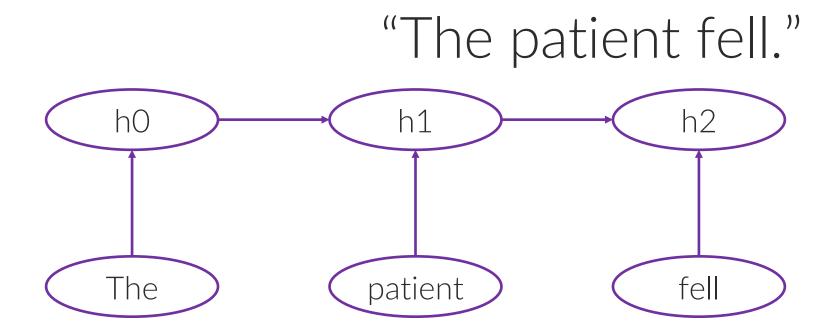
#### Using a recurrent neural network (RNN).





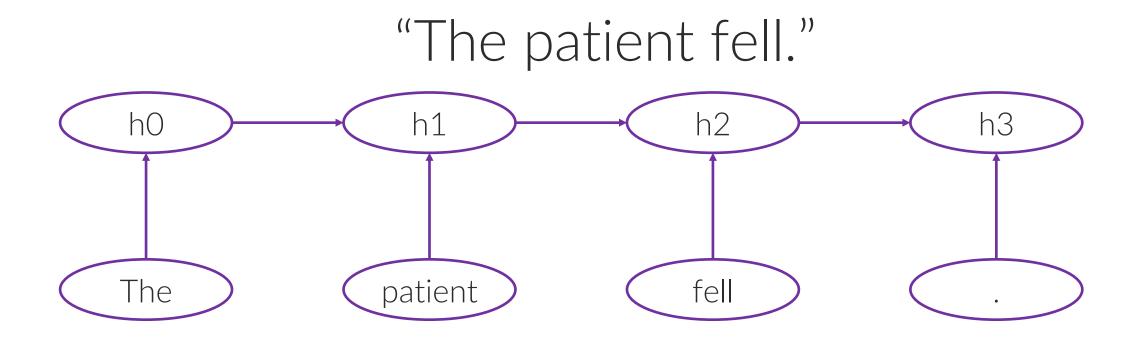
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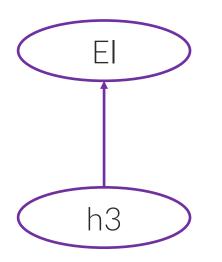
### Using a recurrent neural network (RNN).



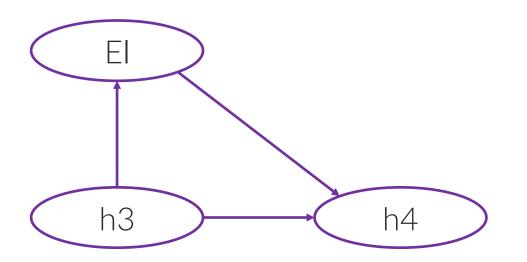


RNN is like a hidden Markov model but doesn't make the Markov assumption and benefits from a vector representation.

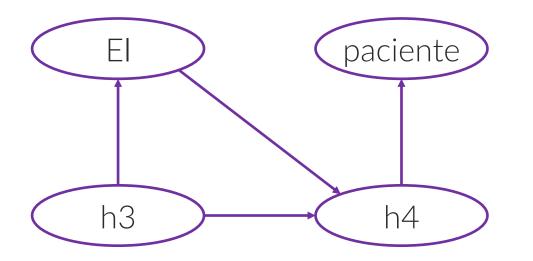




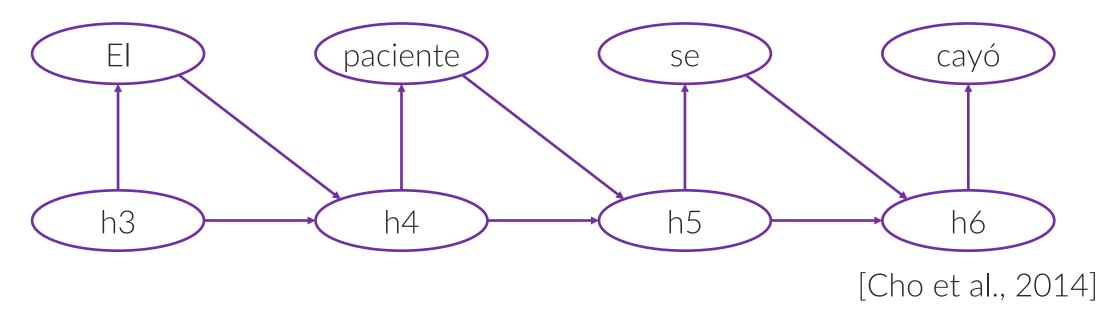








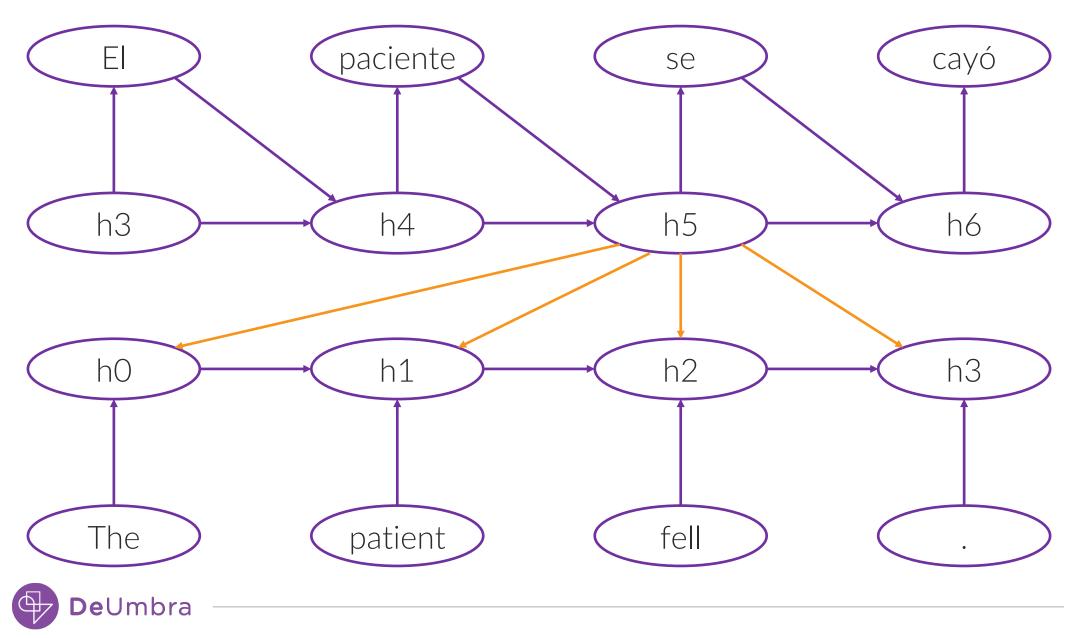




- It keeps generating until it generates a stop symbol.
- It is using a kind of interpolation from a huge set of training data.

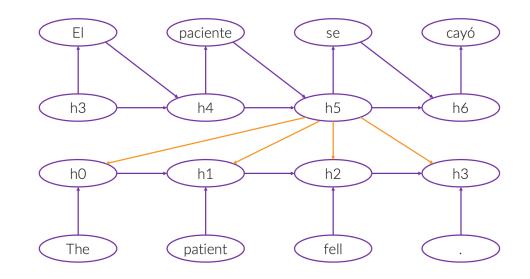


#### Attention [Bahdanau et al., 2014]

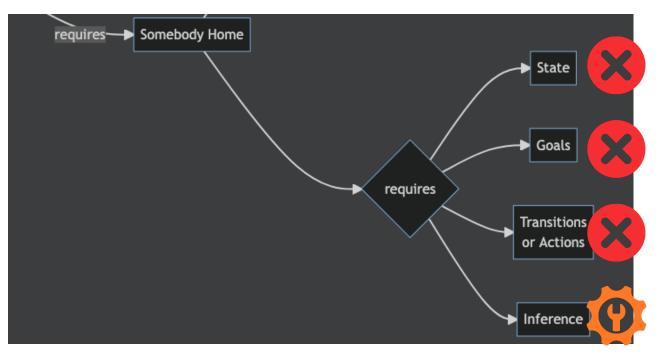


## Transformers: Attention is all you need

https://arxiv.org/abs/1706.03762



# You can't have truth without world interaction



We need to build an AI that knows what a toddler knows before we can build one that understands Wikipedia.

Although ChatGPT could interact with a virtual machine <a href="https://www.engraved.blog/building-a-virtual-machine-inside/">https://www.engraved.blog/building-a-virtual-machine-inside/</a>

Language is a representation medium for the world—it isn't the world itself.

 When we talk, we only say what can't be inferred because we assume the listener has a basic understanding of the dynamics of the world (e.g., if I push a table the things on it will also move)

The inferences are not about the world

Is this stove hot? Ouch!

### Imitation Learning from Video with Transformers

Robots can watch YouTube and learn to imitate, analogous to ChatGPT

Multimodal, language and object manipulation

The trick is the tokenization of events in video, but Google has made some good progress

Robotics Transformer 1 (RT-1)

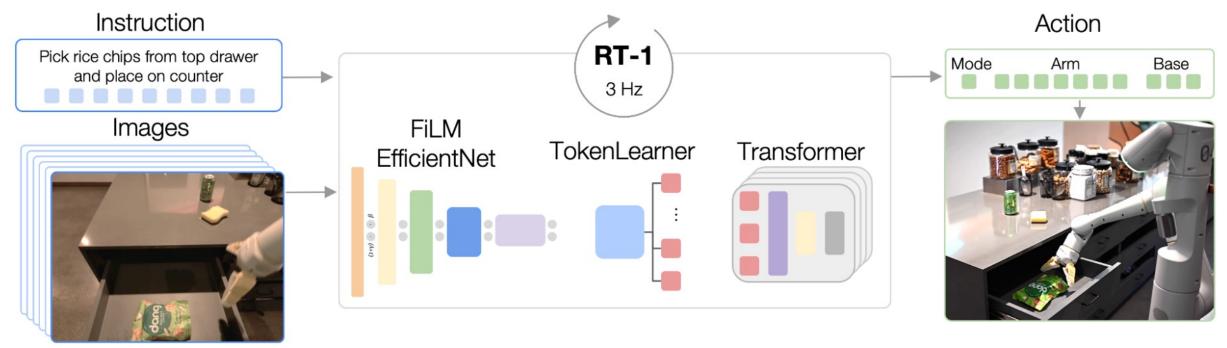
• Transformer model trained by copying demonstrations

• Predict the next most likely action based on what it has learned from the demonstrations <u>https://blog.google/technology/ai/helping-robots-learn-from-each-other/</u> <u>https://ai.googleblog.com/2022/12/rt-1-robotics-transformer-for-real.html</u> <u>https://robotics-transformer.github.io/assets/rt1.pdf</u>



16 subscribers

### Imitation Learning from Video with Transformers



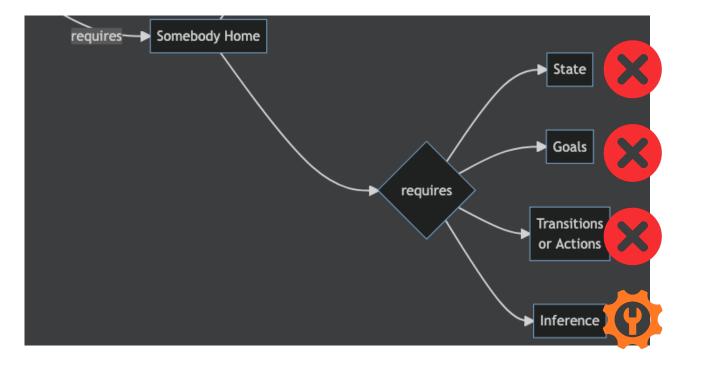
### The trick is the tokenization of events in video, but Google has made some good progress

Image used with permission. Thanks Keerthana Gopalakrishnan! @keerthanpg

Robotics Transformer 1 (RT-1)

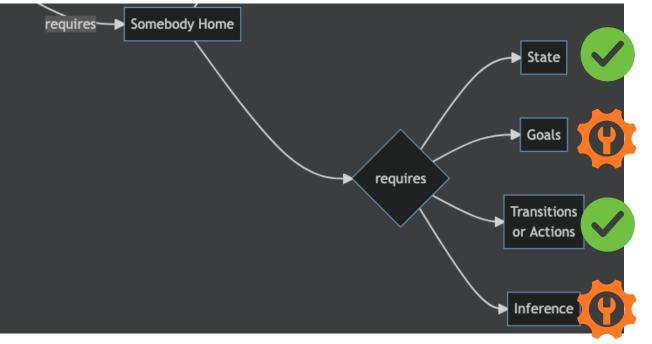
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• Predict the next most likely action based on what it has learned from the demonstrations <u>https://blog.google/technology/ai/helping-robots-learn-from-each-other/</u> <u>https://ai.googleblog.com/2022/12/rt-1-robotics-transformer-for-real.html</u> <u>https://robotics-transformer.github.io/assets/rt1.pdf</u>



Recall the report card for transformer trained on text

### Imitation Learning from Video with Transformers



Using robots in the real or simulated world provides State.

Goals are weak since it is imitation learning.

We have transitions/actions that happen in the real world.

Also limited due to imitation learning

# Reinforcement learning trained in simulation

Instead of building a system that can learn to build its own simulations, we train robots in simulated worlds that we build



Al2Thor by Allen Al https://ai2thor.allenai.org/ Microsoft Flight Simulator <u>https://www.flightsimulator.com/</u>

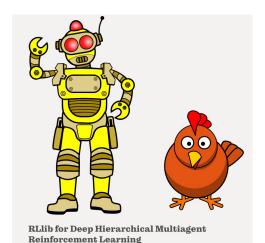
# Reinforcement learning trained in simulation

Instead of building a system that can learn to build its own simulations, we train robots in simulated worlds that we build

There has been some exciting progress in the area from DeepMind and others <a href="https://www.deepmind.com/blog/from-motor-control-to-embodied-intelligence">https://www.deepmind.com/blog/from-motor-control-to-embodied-intelligence</a>

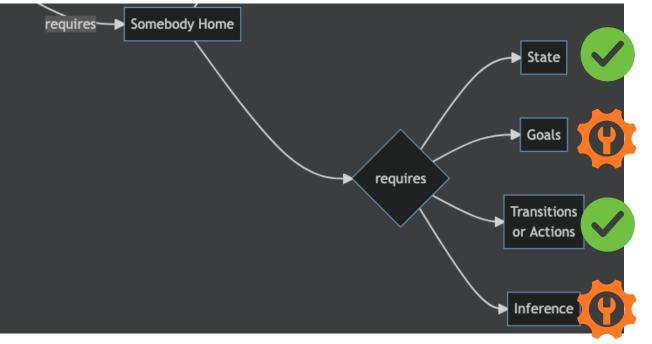
Soccer!

Decision transformers <a href="https://huggingface.co/blog/decision-transformers">https://huggingface.co/blog/decision-transformers</a>



https://deumbra.com/2022/08/rllib-for-deep-hierarchicalmultiagent-reinforcement-learning/

### Imitation Learning from Video with Transformers



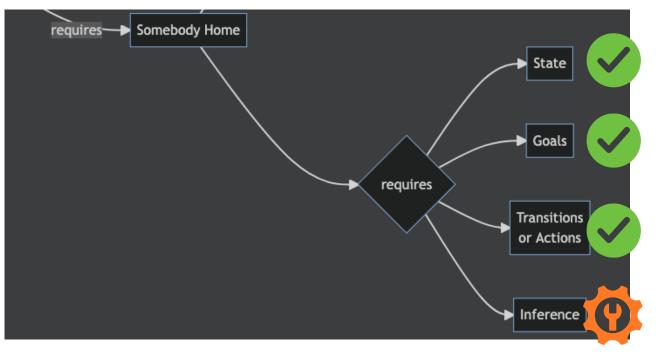
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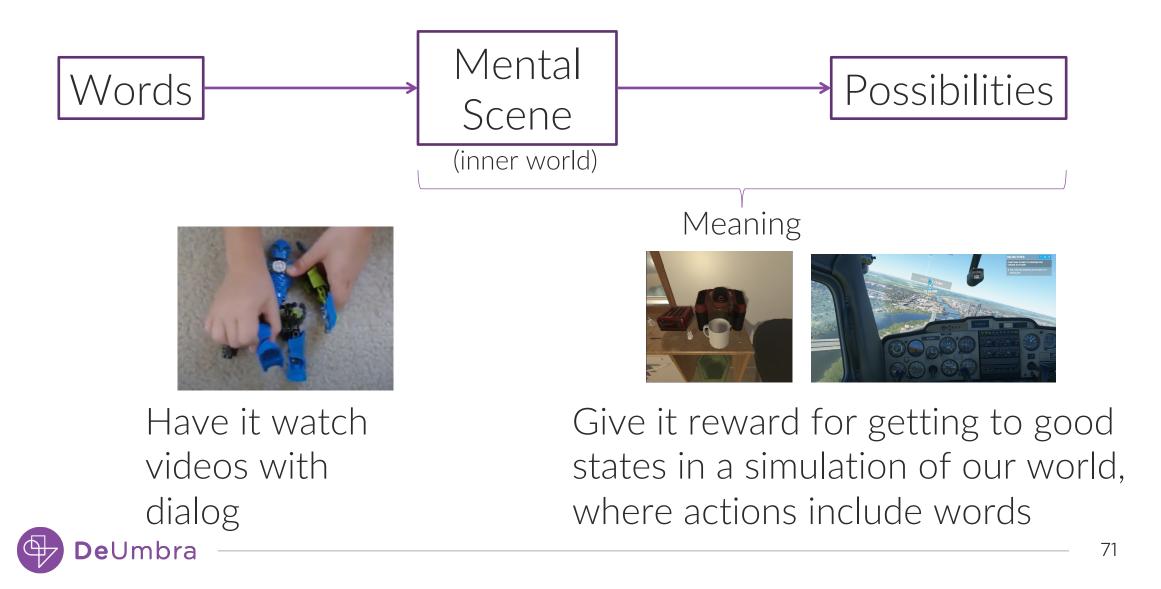
Using robots in the real or simulated world provides State.

Goals are more real with reinforcement learning

We have transitions/actions that happen in the real world.

This will be the challenge to generalize

# How to build someone to talk to using the subsymbolic method



### Conclusion

When we build an AI with somebody home, it will have goals.

It will talk with us to achieve those goals.

It may not be familiar and chatty like ChatGPT.

It will be a little alien and sometimes be hard to understand.

But it will be more reliable because it understands the conversation, and it will be more trustworthy because the mistakes it makes will make sense to us.

It will be somebody worth talking to!

